

Homework I  
Generative Modeling by Transport: Mathematical Foundations

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**Problem 1. A Regression Principle Hidden Inside a Geometry Problem** Let  $X$  be uniformly distributed on the unit circle  $S^1 \subset \mathbb{R}^2$ . Let  $Y \in \mathbb{R}^2$  be an integrable random vector satisfying

$$\mathbb{E}[Y \mid X = x] \cdot x = 0 \quad \text{for almost every } x \in S^1.$$

For a measurable vector field  $u : S^1 \rightarrow \mathbb{R}^2$ , define

$$J[u] = \mathbb{E} \left[ \frac{1}{2} |u(X)|^2 - Y \cdot u(X) \right].$$

- (a) Prove that  $J$  is minimized by  $u_\star(x) = \mathbb{E}[Y \mid X = x]$ .
- (b) Prove that the minimizer is tangent to the circle almost everywhere.
- (c) Now suppose one only minimizes over tangent vector fields  $u(x) \cdot x = 0$ . Prove that the same minimizer is obtained.
- (d) Explain why this is the correct abstract mechanism behind the quadratic objectives for velocities and denoisers in stochastic interpolants.

**Problem 2. Gaussian Smoothing Without Saying “Diffusion”** Let  $Y$  be an arbitrary  $\mathbb{R}^d$ -valued random variable, and let  $Z \sim \mathcal{N}(0, I)$  be independent of  $Y$ . For a positive definite matrix  $A \in \mathbb{R}^{d \times d}$ , define

$$X = Y + AZ.$$

- (a) Prove that  $X$  has a strictly positive  $C^\infty$  density.
- (b) Express its characteristic function in terms of the characteristic function of  $Y$ .
- (c) Prove that for every multi-index  $\alpha$ ,  $\partial^\alpha \rho_X$  is bounded.
- (d) Show that if  $A_n \rightarrow 0$ , then  $\rho_{Y+A_n Z}$  may lose smoothness in the limit.
- (e) Explain why this is the analytic role of  $\gamma(t)z$  in stochastic interpolants.

**Problem 3. A Conservation Law From a Moving Random Cloud** Let  $U$  be a random variable on a probability space, and let  $X_t = F(t, U) \in \mathbb{R}^d$ , where  $F \in C^1([0, 1] \times \Omega; \mathbb{R}^d)$ . Suppose  $X_t$  has a strictly positive smooth density  $\rho(t, x)$  for every  $t$ . Define

$$b(t, x) = \mathbb{E}[\partial_t F(t, U) \mid X_t = x].$$

- (a) Prove that  $\rho$  satisfies

$$\partial_t \rho + \nabla \cdot (b\rho) = 0$$

in the weak sense.

- (b) Give an example where  $b$  is not equal to  $\partial_t F(t, U)$  as a pointwise function of  $x$ , but is a conditional average.
- (c) Suppose  $F(t, U) = a(t)U$ , where  $U \sim \rho_0$ ,  $a(t) > 0$ . Compute  $b(t, x)$  explicitly.
- (d) Verify directly that the density of  $a(t)U$  solves the continuity equation with your  $b$ .

**Problem 4. A Likelihood Formula on a Compact World** Let  $\mathbb{T} = \mathbb{R}/2\pi\mathbb{Z}$  be the circle. Let  $b \in C^1([0, 1] \times \mathbb{T})$ , and let  $X_{s,t}(x)$  solve

$$\frac{d}{dt}X_{s,t}(x) = b(t, X_{s,t}(x)), \quad X_{s,s}(x) = x.$$

Let  $\rho$  solve

$$\partial_t \rho + \partial_x (b\rho) = 0.$$

(a) Prove that along characteristics,

$$\frac{d}{dt} \log \rho(t, X_{s,t}(x)) = -\partial_x b(t, X_{s,t}(x)).$$

(b) Derive the circle analogue of the continuous change-of-variables formula.

(c) Suppose  $b(t, x) = a(t) \sin x$ . Express the likelihood of  $x_1$  in terms of the backward characteristic.

(d) Explain why compactness removes boundary terms in the weak formulation.

**Problem 5. The Invisible Gauge Freedom of Velocity Fields** Let  $\rho(t, x) > 0$  be a smooth probability density on  $[0, 1] \times \mathbb{R}^d$  with sufficient decay at infinity. Suppose  $b$  satisfies

$$\partial_t \rho + \nabla \cdot (b\rho) = 0.$$

- (a) Characterize all smooth vector fields  $\tilde{b}$  that generate the same density path  $\rho(t)$  through the same continuity equation.
- (b) Show that the difference  $\tilde{b} - b$  is of the form  $J/\rho$ , where  $\nabla \cdot J = 0$ .
- (c) In  $d = 1$ , prove that under decay at infinity the velocity field is unique.
- (d) In  $d = 2$ , prove that any compactly supported smooth stream function  $\psi(t, x)$  generates another admissible velocity field

$$\tilde{b} = b + \frac{\nabla^\perp \psi}{\rho}, \quad \nabla^\perp \psi = (\partial_{x_2} \psi, -\partial_{x_1} \psi).$$

- (e) Interpret this as a “gauge freedom” and explain why stochastic interpolants choose a particular velocity by conditional expectation.